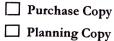


KALYANI UNIT



S.O. NO	Date
Ref No	Section
	Planning

PURCHASE	REQUISITION	2/11/29
		01

FORM NO:-

Print	Date: 9/11/2024
PR No.	Date
K-24-PR-00791	9/11/2024
JOB NO.	BOM NO.
24096C	

Remarks:

	_	
Hold		Passed

Sl.	Item Code	Cat	HSN/SAC	Description/Drawing No	<procu></procu>	<-Factory->	Delivery Within	REM
			Code	Remarks	Qty UOM		<schedule></schedule>	1
1	#24096C18AM1	LP		2600 KW X 4P, VFD COMPATIBLE, 6.6 KV-50 HZ, 3 PHASE FOOT MOUNTED, AC HT SQUIRREL CAGE INDUCTION MOTOR, FOR 2240 MM DIA. DI.BAB-42 COMBUSTION AIR FAN, (VFD COMPATIBLE), MOTOR SHOULD HAVE PT 100 TYPE (DUPLEX) FOR WINDING TEMPERATURE (6 NOS) & RTD DUPLEX TYPE FOR MOTOR BRG. TEMPERATURE (2 NOS.) PROVISION ON MOTOR FOR 4 NOS. VIBRATION SENSOR FIXING, SIZE: M8x1.25Px15 DEEP. PAINT: RAL7030. (FRAME SIZE- AS PER MOTOR MANUFACTURAR). COMPLETE IN ALL RESPECT AS PER TS CURVE & MOTOT SPEC. SHEET ATTACHED. QTY:- 1 NO/FAN. MAKE:- TMEIC/SIEMENS/ABB.	1.000 NO	1.000 NO	09/11/2 5 - 09/11/2 5	P/F

REM: P = Procurement S = Sub-Contract

I = Existing Item Rate; R = Rate Contract; E = Enquiry; Z = Own Make Item (Proc. Not Reqd.)

NOTE : -

- 1 Drawing enclosed herewith.
- 2 Test Certificates & inspection reports to be produced.

24 Indentor

1547/Aksar Ali

Buellion Authorised Signatory 39494

ENGG.DIVN.)

I UNIT

Purchase Copy

Planning Copy

S.O. NO	Date
Ref No	Section
	Planning

PURCHASE REQUISITION

FORM NO:-

Print Date: 9/11/2024 PR No. Date 9/11/2024 K-24-PR-00791 JOB NO. BOM NO. 24096C

Remarks:

Hold Passed

Sl.	Item Code	Cat	HSN/SAC Code	Description/Drawing No Remarks	<procu> Qty UOM</procu>		Delivery Within <schedule></schedule>	REM
2	#24096C28AM1	LP	8501	2600 KW X 4P, VFD COMPATIBLE, 6.6 KV-50 HZ, 3 PHASE FOOT MOUNTED, AC HT SQUIRREL CAGE INDUCTION MOTOR, FOR 2240 MM DIA. DI.BAB-42 COMBUSTION AIR FAN, (VFD COMPATIBLE), MOTOR SHOULD HAVE PT 100 TYPE (DUPLEX) FOR WINDING TEMPERATURE (6 NOS) & RTD DUPLEX TYPE FOR MOTOR BRG. TEMPERATURE (2 NOS.) PROVISION ON MOTOR FOR 4 NOS. VIBRATION SENSOR FIXING, SIZE: M8x1.25Px15 DEEP. PAINT: RAL7030. (FRAME SIZE- AS PER MOTOR MANUFACTURAR). COMPLETE IN ALL RESPECT AS PER TS CURVE & MOTOT SPEC. SHEET ATTACHED. QTY:- 1 NO/FAN. MAKE:- TMEIC/SIEMENS/ABB.	2.000 NO	2.000 NO	09/11/2 5 – 09/11/25	P/E

REM: P = Procurement S = Sub-Contract

I = Existing Item Rate; R = Rate Contract; E = Enquiry; Z = Own Make Item (Proc. Not Reqd.)

NOTE : -

- 1 Drawing enclosed herewith.
- 2 Test Certificates & inspection reports to be produced.

09/11/24 Indentor

1547/Aksar Ali

Smellia Authorised Signatory 39494

ANNEXURE -E-4

NVERTER DUTY 6.6 KV HT MOTOR

Serial No.	Parameters	Description
<u>Serial NO.</u> 1.0	Туре	 HT Squirrel cage induction motor. Voltage grade shall be 6.6 kV. Shall be specifically designed for 6.6kV matching with VFD Output.
		Inverter Duty
2.0	Standard	- IEC: 60034
2.0	Constructional Feature	S
3.0	Frame size and rating	Ac nor IEL.
3.i	Stator Frame	Eabrication Steel/ High grade cast from
3.ii 3.iii	Stator Core	 Laminated sheets of high grade low loss silicon steel
2	Motor body	- Grey iron casting as per IS:210-1978
3.iv 3.v	Casing Feet	tetegral with the motor frame
3.vi	Body Design	 Integral with the momentum other failure due to vibrations normally encountered in heavy industries.
3 vii	Protection for Motor & Bearing	IP – 55 (with canopy for motor if installed outdoor) as per as per IS 4691- (As per IEC standard)
3.viii	Shaft ends & Extension	- Forged Steel shaft Proper drilling and tapping shall be provided for mounting of tachos for speed feedback (if required)
3.ix	Bearings	Anti-friction roller bearing Bearings shall be suitable for running of motor in either direction.
2	Bearing Insulation	Against circulating shaft currents
3.x 3.xi	Hazardous Area safety design	Considered Safe Area
3.xii	Indication of Direction of rotation	By Arrow blocks on non-driving end .Motor shall be capable of unidirectional rotation. -All motors shall be provided with PT100 type
3.xiii	RTD & BTD(PT100type)	-All motors shall be provided with a rise syp- (duple)x6nos or (simple)x12 numbers stator winding temperature detectors & 2nos Bearing (DE & NDE) temperature detectors (Duplex) for monitoring Alarm & Trip conditions.
		-For HT motors, temperature of each RTD (for winding , bearing) should be taken to VFD drive through scanner at VFD panel (2sets of Analogue output shall be considered at scanner, one shall be connected to VFD & other shall be connected to DCS) for monitoring and control. Also through Profinet communication from VFD, temperature parameters will be communicated to main Plant automation system (DCS) for online monitoring.

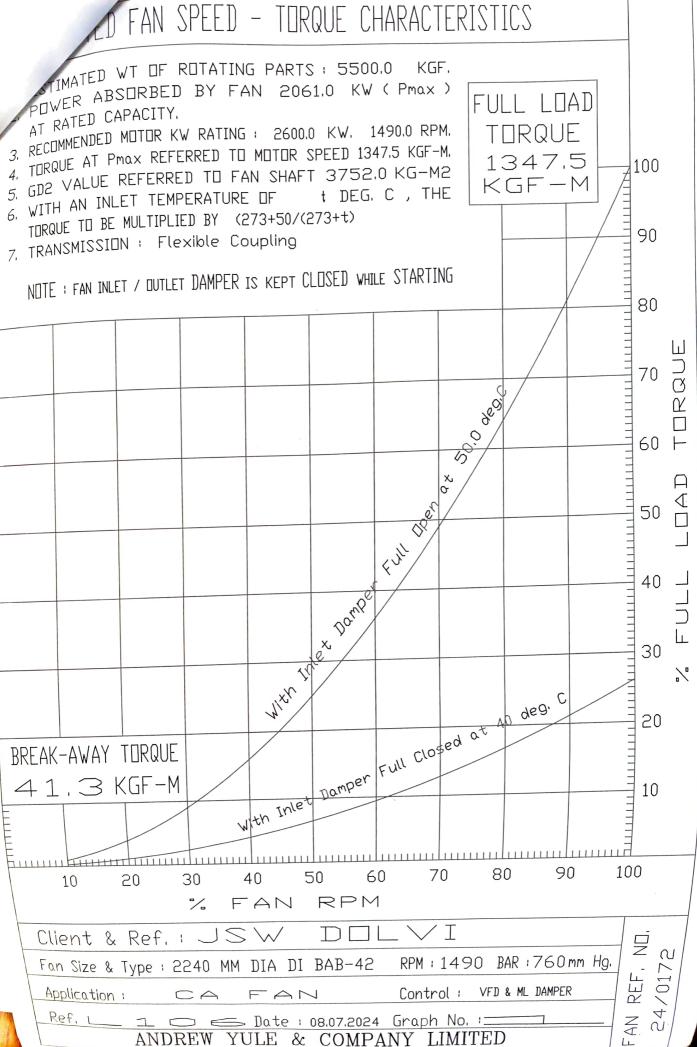


ANNEXURE -E-4

		Limit value contacts for alarm and tripping shall
		be generated in the VFD along with the display of
		winding and bearing temperature.
		- Local Dial Gauge to be provided for DE &
		NDE bearing temperature indicator for motors
0		rated 1000KW and above.
3.xiv	Vibration Probes &	-shall be provided for X and Y axis at DE & NDE
	Vibration monitoring	end of motor bearing.
		-Accordingly vibration pad shall be provided.
		-Vibration monitoring shall be achieved by providing vibration monitors at field (pedestal
		mounted).
		-Vibration monitors shall be connected with VFD
		drive and JSW PLC for monitoring and control.
		-PLC Signal should be 4-20mA.
3.v	Paint shade	RAL 7030
4	Terminal Box	
4.i	Protection	IP:55
4.ii	Туре	Main TB-Phase segregated
		Neutral TB- Phase segregated.
4.iii	Location	Main TB-RHS viewed from DE / On top
		Neutral TB- RHS viewed from DE
4.iv	Suitablity	Termination of XLPE cables with heat
		shrinkable cable end seals
		Each TB to have 2 nos inlets to accommodate
4	Davassible	any parallel cables as required.
4.v	Reversible	To suit cable entry from TOP, Bottom
4.vi	Earthing stud	Inside Main TB for Protective earth conductor termination
4.vii	No of additional	Separate TBs for space Heater, RTD, BTD
- T. V 11	Terminal Boxes	Vibration monitor etc.
4.viii	Fault withstand (Min.)	Rated short circuit level of the system voltage
		for 0.25Sec.
4.ix	Interchangeability	Line side & neutral side TB s shall be
		interchangeable.
5.0	Cooling	CACA.
5.0	Quality of Operations	
5.i	Vibration intensity	Shall be as per IEC Standards
S.ii	Noise level	Shall be as per IEC Standards
5. iii	Balancing	Motors shall be dynamically balanced with
7.0		full/half key on the shaft- end and fan
7.0 7.i	Electrical Design	
1.1	Efficiency	High efficiency design of 95% or
7.ii	Ctartize 2 Di 11	higher at Full load
1.11	Starting & Direction of Rotation	Variable Frequency Drive.
7.iii	Min Voltage for start &	Direction of Rotation -Bidirectional 85% of rated Voltage at terminal
	Run	sono orrated voltage at terminar
7.iv	Starting Torque	1.6 time from rated torque (As per IEC
7.v	Storting Oursel	Standards)
r.V	Starting Current	Controlled by VFD. Limitation as per
		VFD design.

ANNEXURE -E-4

7. vi	Load Type	Variable Torque for Fan application.
7.vi 7.vii	Peak transient voltage	Shall be as per VFD manufacturer
7.00		requirement.
7.viii	Minimum rise time	Shall be as per VFD manufacturer
1.000		requirement.
7.ix	No of pole	4 pole preferable
7.x	Duty	Continuous, inverter duty and suitable
		for Process Fan application
7.xi	Stall time	 Minimum 60 sec for constant torque
1.70		applications
		 Higher stall time as per application
		requirement
7.xii	Start permissible	3 cold/2 Hot
7.xiii	Start/Hour	6 equally spaced
7.xiv	Overload capability	Capable of withstanding 160% Overload for 15
		sec.
7.xv	Max speed permissible	120% over speed for 2 minutes Class H with temp Rise limited to Class F
7.xvi	Insulation	Insulation materials with additional phase
		insulating material extra end turn bracing
7.xvii	Impregnation of wound	VPI
(.XVII	stator	
7.xviii	Derating of VFD	As per manufacturing and design
		standards
7.xix	Space Heater	Required & automatically off during
		RUN
7.xx	Surge protection	As required



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